# Modelling non-stationarity in asymptotically independent extremes (in review)

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- My PhD: estimating return curves at extreme values.
- Given two variables,

$$RC(p) := \{(x, y) \in \mathbb{R}^2 \mid Pr(X > x, Y > y) = p\},\$$

where p is very small.

- Provides a summary of extremal dependence.
- Return level extension.

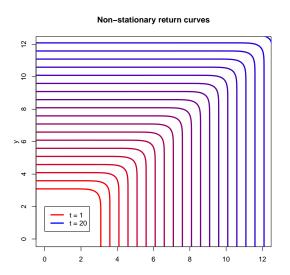
- ▶ In practice, we wish to estimate return curves for combinations of environmental variables (temperature, relative humidity, wind speed etc.).
- Such variables exhibit non-stationarity.

- Return curves lack meaning in the non-stationary setting, motivating an extended definition.
- ▶ Given  $\{X_t, Y_t\}$  with **covariates Z**<sub>t</sub>,  $t \in \{1, 2, ..., T\}$ ,

$$RC_{\mathbf{z}_t}(p) := \{(x, y) \in \mathbb{R}^2 \mid \Pr(X_t > x, Y_t > y \mid \mathbf{Z}_t = \mathbf{z}_t) = p\}.$$

▶ End goal: estimating non-stationary return curves.





- ▶ To estimate return curves, we require **models** for evaluating the **joint tail** of (X, Y).
- Frameworks for assessing extremal dependence.
- Classification of extremal dependence given by the coefficient χ:

$$\chi = \lim_{u \to 1} \Pr(F_Y(Y) > u \mid F_X(X) > u) \in [0, 1].$$

- $\chi = 0 \Rightarrow$  asymptotic independence.
- $\chi > 0 \Rightarrow$  asymptotic dependence.

- Classical models based on framework of multivariate regular variation.
- ▶ Given a random vector (X, Y) with standard Fréchet margins, define R := X + Y and W := X/(X + Y):

$$\lim_{r\to\infty}\Pr(W\in B,R>sr\mid R>r)=H(B)s^{-1},\ s>1.$$

► *H* is termed the **spectral measure** 

- ▶ Downside: multivariate regular variation is only **suitable** in the case of **asymptotic dependence**.
- Extremal dependence structure **unknown** in practice.
- Motivates models that can capture **both** extremal dependence regimes.

- First model proposed in Ledford and Tawn (1996).
- $\triangleright$  Given random vector (X, Y) on standard exponential margins,

$$\Pr(X > u, Y > u) = \Pr(\min(X, Y) > u) \rightarrow L(e^u) \exp(-u/\eta),$$
  
as  $u \rightarrow \infty$ , with  $L$  slowly varying and  $\eta \in (0, 1].$ 

- $\eta = 1 \Rightarrow$  asymptotic dependence.
- $\eta < 1 \Rightarrow$  asymptotic independence.
- ► Equal marginal growth rates ⇒ **limited applicability**.

- ▶ Ledford and Tawn (1996) model was **extended** in Wadsworth and Tawn (2013).
- ▶ Given any  $ray w \in [0, 1]$ ,

$$\Pr(X > wu, Y > (1 - w)u) =$$

$$\Pr\left(\min\left\{\frac{X}{w}, \frac{Y}{1 - w}\right\} > u\right) \to L(e^u \mid w) \exp(-\lambda(w)u),$$

as  $u \to \infty$ , with L slowly varying.

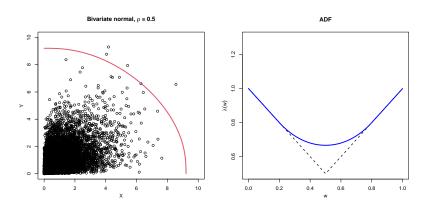
- ▶  $\lambda(w) \ge \max(w, 1 w)$  is termed the **angular dependence** function (ADF).
- **Summarises** the joint tail behaviour.
- Captures both asymptotic dependence (lower bound) and asymptotic independence.
- ► Ledford and Tawn (1996) recovered when  $w = 0.5 \Rightarrow \eta = 1/(2\lambda(0.5))$ .
- ▶ Allows evaluation of extremal dependence in all regions.

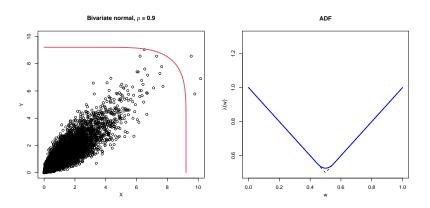
Define 
$$K_w := \min \left\{ \frac{X}{w}, \frac{Y}{1-w} \right\}$$
.

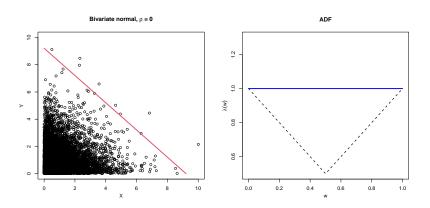
$$\Pr(K_w > u + v | K_w > u) \rightarrow \exp(-\lambda(w)v),$$

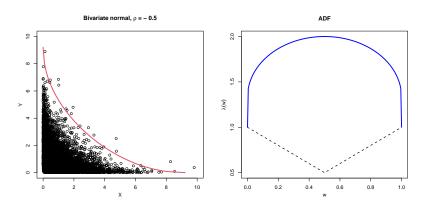
as  $u \to \infty$  for any v > 0.

**Simplified**:  $(K_w - u \mid K_w > u) \sim \text{Exp}(\lambda(w))$  for all  $w \in [0,1]$ .









- ▶ Let  $\{X_t, Y_t\}$  with  $\mathbf{Z}_t$ ,  $t \in \{1, 2, ..., T\}$ , denote a **non-stationary process**.
- ► Two forms of non-stationarity can exist.
  - 1. Trends in marginal extremes tail of  $X_t$  ( $Y_t$ ). Well studied.
  - 2. Trends in extremal dependence. **Sparse literature.**
- Must account for both forms in our estimation procedure.
- We focus on second problem and present a novel modelling technique.

- ► **Few approaches** for capturing non-stationarity in extremal dependence.
- ► Almost all developed using multivariate regular variation framework.
- Asymptotically independent case not well studied.

We propose an **non-stationary extension** to the Wadsworth and Tawn (2013) model.

With  $\{X_t, Y_t\}$  on standard exponential margins and  $w \in [0, 1]$ :

- 1. Define  $K_{w,t} := \min \left\{ \frac{X_t}{w}, \frac{Y_t}{1-w} \right\}$ .
- 2. Assume

$$\Pr\left(K_{w,t} > v + u \middle| K_{w,t} > u, \mathbf{Z}_t = \mathbf{z}_t\right) \to \exp(-\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)v),$$

as  $u \to \infty$  for any v > 0 and  $t \le T$ .

 $\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)$  is termed the **non-stationary** ADF.



Can estimate via quantile regression on  $K_{w,t}$ :

- ▶ Select **probabilities**  $q_1 < q_2 < 1$  close to 1.
- $\blacktriangleright$  For a **fixed** w, find  $u_1$  and  $u_2$  such that

$$\Pr\left(K_{w,t} \leq u_1 \middle| \mathbf{Z}_t = \mathbf{z}_t\right) = q_1$$
  
 $\Pr\left(K_{w,t} \leq u_2 \middle| \mathbf{Z}_t = \mathbf{z}_t\right) = q_2.$ 

lacksquare As  $q_1 o 1$ ,  $u_1 o \infty$ , so we have

$$\frac{1 - q_2}{1 - q_1} = \exp\{-\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)(u_2 - u_1)\}$$



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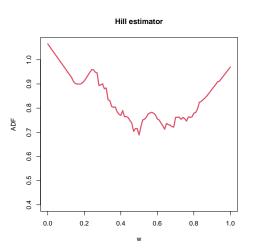
Estimator given by

$$\hat{\lambda}(w \mid \mathbf{Z}_t = \mathbf{z}_t) = -\frac{1}{u_2 - u_1} \log \left( \frac{1 - q_2}{1 - q_1} \right)$$

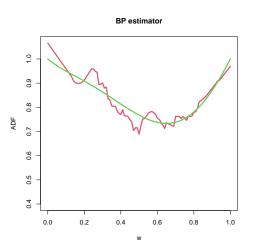
In practice, there are a few additional steps.

- Averaging over different values for  $q_1$  and  $q_2$ . Bias-variance trade-off.
- Smoothing.
- Imposing theoretical properties of ADF.

Estimator is **pointwise** - unrealistic.



Smooth using **Bernstein-Bézier polynomials** (Marcon et al., 2017).



See Murphy-Barltrop and Wadsworth (2022) for further details.



We can use non-stationary ADFs to estimate return curves.

$$\Pr(X_t > x, Y_t > y \mid \mathbf{Z}_t = \mathbf{z}_t) = p$$

▶ Given any ray  $w \in [0,1]$  and t, define r as

$$r := -\frac{1}{\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)} \log \left( \frac{p}{1-q} \right).$$

with q < 1 - p < 1.

Implies

$$\frac{p}{1-q} = \exp(-\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)r).$$



- Let (x,y) := (w(r+u), (1-w)(r+u)), with u equal to the q-th quantile of  $K_{w,t}$ .
- We have

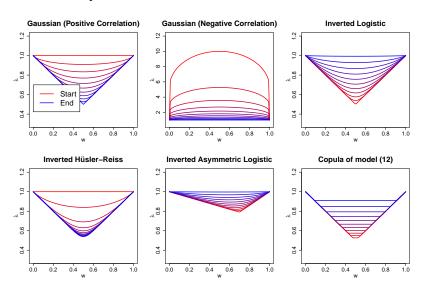
$$\begin{aligned} & \Pr(X_t > x, Y_t > y \mid \mathbf{Z}_t = \mathbf{z}_t) \\ & = \Pr(X_t / w > r + u, Y_t / (1 - w) > r + u \mid \mathbf{Z}_t = \mathbf{z}_t) \\ & = \Pr(\min\{X_t / w, Y_t / (1 - w)\} > r + u \mid \mathbf{Z}_t = \mathbf{z}_t) \\ & = \Pr(K_{w,t} > r + u \mid \mathbf{Z}_t = \mathbf{z}_t) \end{aligned}$$

$$\begin{aligned} & \Pr(K_{w,t} > r + u \mid \mathbf{Z}_t = \mathbf{z}_t) \\ &= \Pr(K_{w,t} > r + u \mid K_{w,t} > u, \mathbf{Z}_t = \mathbf{z}_t) \\ &\times \Pr(K_{w,t} > u \mid \mathbf{Z}_t = \mathbf{z}_t) \\ &\approx \exp\{-\lambda(w \mid \mathbf{Z}_t = \mathbf{z}_t)r\} \Pr(K_{w,t} > u \mid \mathbf{Z}_t = \mathbf{z}_t) \\ &= \frac{p}{1-q} \times 1 - q = p, \end{aligned}$$

So (x, y) is a point on the return curve  $RC_{\mathbf{z}_t}(p)$ . Repeat for all w and t.

## Simulation study

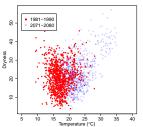
I won't bore you with the details.

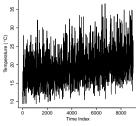


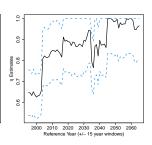
- ► Take the 1980-2080 **temperature** and **relative humidity** UKCP18 data for the nuclear site at Heysham, UK.
- We focus on summer data only.



- ▶ Suppose 0 < RH < 100 represents relative humidity. We define a 'dryness' variable: Dr := 100 RH.
- Combination of high temperature and high dryness typical of drought-like conditions.
- ► This is a concern for nuclear regulators (Knochenhauer and Louko, 2004).
- ▶ Understanding relationship between the extremes could allow for better risk management.

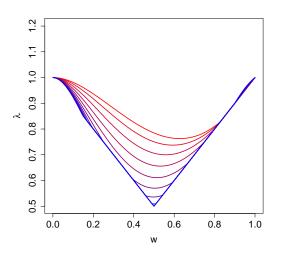




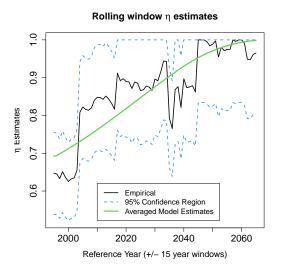


- 1. **Remove marginal trends** using methods proposed in Davison and Smith (1990) and Eastoe and Tawn (2009).
- 2. Transform data to exponential margins.
- 3. Estimate non-stationary ADF.
- 4. Calculate return curve estimates up to the year 2080.

Red = start, blue = end.



#### Motivating example - UKCP18 data



(Model estimate given by 
$$\hat{\eta}_t = [2\hat{\lambda}(0.5 \mid \mathbf{Z}_t = \mathbf{z}_t)]^{-1}$$
)

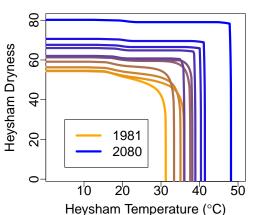


## Motivating example - UKCP18 data

Many nuclear facilities built to withstand  $10^{-4}$  annual exceedance probability events.

Such events will not be fixed in the non-stationary setting.

#### 10,000 Year Return Curves



#### Conclusions

- We have developed a novel modelling framework for asymptotically independent, non-stationary data structures.
- Can estimate non-stationary return curves that reflect observed trends.
- Our work makes a **contribution** to a particularly **sparse field**.

#### Discussion

- ▶ Uncertainty difficult to quantify in any meaningful way.
- ► Modelling choices quantile levels, number of quantile pairs, degree of polynomial, covariate function forms.
- Assumes we can **perfectly account** for marginal non-stationarity **never** the case in practice.
- No theoretical results.
- Lots of avenues for future research.

Thanks for listening! Does anyone have any questions?

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#### References II

Murphy-Barltrop, C. J. R. and Wadsworth, J. L. (2022). Modelling non-stationarity in asymptotically independent extremes. *Preprint*.

Wadsworth, J. L. and Tawn, J. A. (2013). A new representation for multivariate tail probabilities. *Bernoulli*, 19(5 B):2689–2714.

## Averaging over quantiles

- ▶ How do we select  $q_1$  and  $q_2$ ? Bias-variance trade-off
- We instead consider a range of quantile pairs simultaneously and compute an average estimator
- $\{(q_{1,j},q_{2,j}) \mid 1 \leq j \leq m\}$  be quantiles near one, with  $q_{1,j} < q_{2,j} < 1$

$$\bar{\lambda}_{QR}(w \mid \mathbf{z}_t) := \frac{1}{m} \sum_{j=1}^{m} \hat{\lambda}_j(w \mid \mathbf{z}_t).$$

Found this estimator to outperform individual pairs.

## Smoothing

- ▶  $\bar{\lambda}_{QR}$  is pointwise for each ray  $w \in [0,1]$  so **horrible and bumpy**!
- Non-smooth ADF estimates that we would not expect to observe in practice.
- Use parametric polynomial functions to get a smooth estimate.
- ▶ Bernstein-Bézier polynomials of degree k > 0

$$f(w) = \sum_{i=0}^{k} \alpha_i \binom{k}{i} w^i (1-w)^{k-i}$$

with coefficients  $\alpha_i \in [0,1]$  for each i

# Smoothing

- In standard form, this polynomial is fixed.
- We extend to allow covariate influence.
- ▶ Also,  $0 \le f(w) \le 1$ : but  $\lambda$  can be **above** 1!
- Propose family

$$f_t(w) = \sum_{i=0}^k \beta_i(\mathbf{z}_t) \binom{k}{i} w^i (1-w)^{k-i} : \beta(\mathbf{z}_t) \in [0,\infty)^{k+1}$$

 $\beta_i: \mathbb{R}^p \to [0,\infty)$  are positive functions of covariates for all i

 $\beta_0 = \beta_k = 1.$ 

# Smoothing

- **Goal**: estimate  $f_t$  for all t.
- We propose **parametric forms** for the coefficient functions e.g.  $\beta_i(\mathbf{z}_t) = \exp(a_i + b_i \mathbf{z}_t)$  with  $a_i, b_i \in \mathbb{R}$ .
- Find  $\hat{a}_i$ ,  $\hat{b}_i$  for all i by **minimising**

$$\left| \bar{\lambda}_{QR}(w \mid \mathbf{z}_t) - f_t(w) \right|$$

over all w and t.

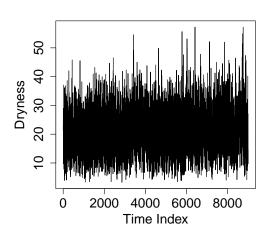
▶ Define resulting estimator to be  $\bar{\lambda}_{BP}(\cdot \mid \mathbf{z}_t)$ 



## Theoretical properties.

- ▶ We impose some theoretical properties on both estimators.
- Ensures lower bound and endpoints are satisfied.
- $ightharpoonup \lambda(w) \ge \max(w, 1-w)$
- $\lambda(0) = \lambda(1) = 1$

## **Dryness**



## Marginal trends

